**Door1 parameter**

long position\_start 0x00C8

long position\_end 0x00CA

long position\_open\_end 0x00CC 暂时未用，预留地址

//~~~~~~~~~~~~~~~~~~~

long speed\_max\_open 0x00CE

long speed\_max\_close 0x00D0

long speed\_crawl 0x00D2

int speed\_fall\_ratio\_factor 0x00D4

int speed\_low\_limit 0x00D6

int speed\_lock\_status 0x00D8

//~~~~~~~~~~~~~~~~~~~

int lenght\_crawl\_open 0x00D8

int lenght\_crawl\_close 0x00DA

int lenght\_end\_open 0x00DC

int lenght\_end\_close 0x00DE

int lenght\_hold\_close\_max 0x00E0

int lenght\_hold\_close\_min 0x00E2

int lenght\_amble\_open 0x00E4

//~~~~~~~~~~~~~~~~~~

int current\_limit\_NO1 0x00E6

int current\_limit\_NO2 0x00E8

int current\_limit\_NO3 0x00EA

int current\_limit\_NO4 0x00EC

int current\_keep\_open 0x00EE

int current\_keep\_close 0x00F0

int current\_history\_max 0x00F2

int current\_limit\_hardware 0x00F4

//~~~~~~~~~~~~~~~~~

int count\_open\_fault->unsigned char

int count\_close\_fault->unsigned char

//~~~~~~~~~~~~~~~~~

int time\_open\_fault\_hold 0x00F6

int time\_open\_hold 0x00F8

int time\_opening\_mode\_hold 0x00FA

int time\_accelerate\_min 0x00FC

int time\_speed\_low 0x00FE

//~~~~~~~~~~~~~~~~~

int door\_stauts\_power\_low 0x0100

int door\_running\_mode 0x0102

int door\_can\_mode 0x0104

int door\_running\_test\_mode 0x0106

int door\_accelerate\_step 0x0108

long door\_run\_count 0x010A

***long door\_run\_history\_count 0x0000***

long door\_current\_integration\_max 0x010C

int door\_battery\_enable 0x010E

//~~~~~~~~~~~~~~~~~

int pwm\_rate\_min 0x0112

int pwm\_rate\_max 0x0114

int pwm\_factor\_drive 0x0116

int pwm\_factor\_undrive 0x0118

int pwm\_factor\_brake 0x011A

int pwm\_factor\_reverse 0x011C

int pwm\_reverse\_permit 0x011E

int pwm\_uniform\_no\_reduce 0x0120

int pwm\_crawl\_end\_no\_reduce 0x0122

int pwm\_brake\_allow\_reduece 0x0124

int pwm\_pid\_regulate\_cycle 0x0126

//~~~~~~~~~~~~~~~~~

int temperature\_limit\_high 0x0128

int temperature\_limit\_low 0x012A

int temperature\_history\_max 0x012C

//~~~~~~~~~~~~~~~~~~~

***int error\_code\_index***

***int error\_code[0]***

***int error\_code[1]***

***int error\_code[2]***

***int error\_code[3]***

***int error\_code[4]***

***int error\_code[5]***

***int error\_code[6]***

***int error\_code[7]***

***int error\_code[8]***

***int error\_code[9]***

//~~~~~~~~~~~~~~~~~~

***int register\_probation\_period***

***int register\_random\_number***

***int register\_run\_mode***

***int register\_power\_hours***

**Door2 parameter**

long position\_start 0x0258

long position\_end 0x025A

long position\_open\_end 0x025C 暂时未用，预留地址

//~~~~~~~~~~~~~~~~~~~

long speed\_max\_open 0x025E

long speed\_max\_close 0x0260

long speed\_crawl 0x0262

int speed\_fall\_ratio\_factor 0x0264

int speed\_low\_limit 0x0266

//~~~~~~~~~~~~~~~~~~~

int lenght\_crawl\_open 0x0268

int lenght\_crawl\_close 0x026A

int lenght\_end\_open 0x026C

int lenght\_end\_close 0x026E

int lenght\_hold\_close\_max 0x0270

int lenght\_hold\_close\_min 0x0272

int lenght\_amble\_open 0x0274

//~~~~~~~~~~~~~~~~~~

int current\_limit\_NO1 0x0276

int current\_limit\_NO2 0x0278

int current\_limit\_NO3 0x027A

int current\_limit\_NO4 0x027C

int current\_keep\_open 0x027E

int current\_keep\_close 0x0280

int current\_history\_max 0x0282

int current\_limit\_hardware 0x0284

//~~~~~~~~~~~~~~~~~

int count\_open\_fault->unsigned char

int count\_close\_fault->unsigned char

//~~~~~~~~~~~~~~~~~

int time\_open\_fault\_hold 0x0286

int time\_open\_hold 0x0288

int time\_opening\_mode\_hold 0x028A

int time\_accelerate\_min 0x028C

int time\_speed\_low 0x028E

//~~~~~~~~~~~~~~~~~

int door\_stauts\_power\_low 0x0290

int door\_running\_mode 0x0292

int door\_can\_mode 0x0294

int door\_running\_test\_mode 0x0296

int door\_accelerate\_step 0x0298

long door\_run\_count 0x029A

***long door\_run\_history\_count 0x0064***

long door\_current\_integration\_max 0x029C

int door\_battery\_enable 0x029E

int speed\_lock\_status 0x02A0

//~~~~~~~~~~~~~~~~~

int pwm\_rate\_min 0x02A2

int pwm\_rate\_max 0x02A4

int pwm\_factor\_drive 0x02A6

int pwm\_factor\_undrive 0x02A8

int pwm\_factor\_brake 0x02AA

int pwm\_factor\_reverse 0x02AC

int pwm\_reverse\_permit 0x02AE

int pwm\_uniform\_no\_reduce 0x02B0

int pwm\_crawl\_end\_no\_reduce 0x02B2

int pwm\_brake\_allow\_reduece 0x02B4

int pwm\_pid\_regulate\_cycle 0x02B6

//~~~~~~~~~~~~~~~~~

int temperature\_limit\_high 0x02B8

int temperature\_limit\_low 0x02BA

int temperature\_history\_max 0x02BC

//~~~~~~~~~~~~~~~~~~~

***int error\_code\_index***

***int error\_code[0]***

***int error\_code[1]***

***int error\_code[2]***

***int error\_code[3]***

***int error\_code[4]***

***int error\_code[5]***

***int error\_code[6]***

***int error\_code[7]***

***int error\_code[8]***

***int error\_code[9]***

//~~~~~~~~~~~~~~~~~~

***int register\_probation\_period***

***int register\_random\_number***

***int register\_run\_mode***

***int register\_power\_hours***